

OPERATING INSTRUCTIONS

Differential Hall Effect Speed Sensor DSD xx10.01 .02 AxV



Product ID

| Type # | Product # | Drawing # |
|------------------|------------|-------------------|
| DSD 1210.01 ATV | 374Z-04059 | 4-110829d-1 |
| DSD 1210.01 AHV | 374Z-04163 | 4-110829d-1 |
| DSD 1410.01 ATV | 374Z-04164 | 4-111499d-1 |
| DSD 1410.01 AHV | 374Z-04165 | 4-111499d-1 |
| DSD 1610.01 ATV | 374Z-04166 | 4-111500d-1 |
| DSD 1610.01 AHV | 374Z-04167 | 4-111500d-1 |
| DSD 1810.01 ATV | 374Z-04168 | 4-110830d-1 |
| DSD 1810.01 AHV | 374Z-04169 | 4-110830d-1 |
| DSD 2210.01 ATV | 374Z-04170 | 4-110831d-1 Rev.1 |
| DSD 2210.01 A1TV | 3742607347 | 4-110831d-1 Rev.1 |
| DSD 2210.01 AHV | 374Z-04171 | 4-110831d-1 Rev.1 |
| DSD EH10.02 AHV | 374Z-05627 | 114609 Rev.01 |

| General | | | |
|--------------------------------------|--|--|--|
| Function | The sensors DSD xx10.01 .02 AxV sensors are suitable, in conjunction with a pole wheel, for generating square wave signals proportional to rotary speeds. They have a static behaviour, so that pulse generation is guaranteed down to a speed corresponding to a frequency of 0 Hz. The monitoring elements consist of an magnetically biased differential hall effect semiconductor. The differential structure requires that the sensor must be oriented. | | |
| Technical data | <u> </u> | | |
| Supply voltage | 8 VDC to 30 VDC, protected against transient overvoltages | | |
| Current consumption | Max. 18 mA (without load) | | |
| Signal output | Square wave signal Push-pull outputs: I_{max} = ± 20 mA | | |
| | with pull-up resistor (for I= I_{max}): U_{low} < 2.5 V, U_{high} > 0.95 * U_{supply} with pull-down resistor (for I= I_{max}): U_{low} < 0.1 V, U_{high} > U_{supply}-4.0 V | | |
| | The outputs are short circuit proof and protected against reverse polarity. | | |
| Frequency range | 0 Hz 20 kHz | | |
| Electromagnetic compatibility (EMC): | With cable shield connected to the supply negative pole. Noise generator between housing and electronics | | |
| | 1.5 kV/1.5 μs/max.5Hz (Source resistance 500 Ohm) | | |
| | 2.0 kV/HF-Bursts (Level 4 in accordance with IEC 801-4) | | |
| | 2.5 kV/1 MHz damped resonance (Class III in accordance with IEC 255-4) | | |
| Housing | Stainless steel 1.4305, front side sealed hermetically and resistant against splashing water, oil, conducting carbon- or ferrous dust and salt mist. Electronic components potted in chemical and age proof synthetic resin. Max. allowable pressure on sensor head: 10 bar Dimensions according to drawing. | | |
| Mounting torque (max.) | 12 Nm for M12x1 25 Nm for M14x1 35 Nm for M16x1 50 Nm for M18x1 75 Nm for M22x1 | | |

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IN CHARGE OF SPEED

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Connector

| Sensor type | Jaquet part number of connector |
|------------------|---------------------------------|
| DSD 1210.01 ATV | 820A-35922 |
| DSD 1210.01 AHV | 820A-35922 |
| DSD 1410.01 ATV | 820A-35731 |
| DSD 1410.01 AHV | 820A-35731 |
| DSD 1610.01 ATV | 820A-35731 |
| DSD 1610.01 AHV | 820A-35731 |
| DSD 1810.01 ATV | 820A-35731 |
| DSD 1810.01 AHV | 820A-35731 |
| DSD 2210.01 ATV | 820A-35731 |
| DSD 2210.01 A1TV | 820A-35731 |
| DSD 2210.01 AHV | 820A-35731 |
| DSD EH10.02 AHV | 820A-36584 |

| Jaquet connector code | Connector | | |
|-----------------------|--|--|--|
| | Lemo ERA-2S-304 CLL | | |
| | Operating temperature: -55°C to +250°C | | |
| 820A-35731 | Plug-and-socket connection: IP50 | | |
| | Lemo ERA-0S-304 CLL | | |
| | Operating temperature: -55°C to +250°C | | |
| 820A-35922 | Plug-and-socket connection: IP50 | | |
| | Escha EWAS4, 4 pole connector, M12x1, material | | |
| | PA66-G25, male plug, gold plated pins | | |
| | Operating temperature: -55°C to +125°C | | |
| 820A-36584 | Plug-and-socket connection: IP67 | | |

| Accessories | According dimensional drawing. | | |
|-----------------------------|---|--|--|
| Requirements for pole wheel | Toothed wheel of a magnetically permeable material (e.g. Steel 1.0036) Optimal performance with | | |
| | Involute gear | | |
| | Tooth width > 10 mm | | |
| | Side offset < 0.2 mm | | |
| | Eccentricity < 0.2 mm | | |
| Air gap between sensor and | Air gap between pole wheel (involute gear) and sensor housing: | | |
| pole wheel | Module 1: 0.10.5 mm | | |
| | Module 2: 0.11.3 mm | | |
| | • ≥ Module 4: 0.11.5 mm | | |
| Insulation | Housing and electronics galvanically separated (500 V/50 Hz/ 1 min) | | |
| Protection class | IP68 (head) and connector according to list | | |
| Vibration immunity | 5 g in the range of 5 2000 Hz | | |
| Shock immunity | 50 g for 20 ms, half sine wave | | |
| Temperature | Operating temperature of entire sensor: | | |
| - | • Version T: -40° +85°C | | |
| | Version H: -40° +125°C | | |

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IN CHARGE OF SPEED

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| Further Information | | | |
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| Safety | All mechanical installations must be carried out by an expert. General safety requirements have to be met. | | |
| Connection | The sensors must be connected according to sensor drawing. Sensor wires are susceptible to radiated noise. Therefore, the following points have to be considered when connecting a sensor: The sensor wires must be laid as far as possible from large electrical machines. They must not run parallel in the vicinity of power cables. The maximum permissible cable length is dependent upon the sensor voltage, the cable routing, along with cable capacitance and inductance. However, it is advantageous to keep the distance between sensor and instrument as short as possible. The sensor cable may be lengthened via a terminal box located in an IP20 connection area in accordance with EN 60529. | | |
| Installation | The sensor has to be aligned to the pole wheel according to the sensor drawing. Deviations in positioning may affect the performance and decrease the noise immunity of the sensor. During installation, the smallest possible pole wheel to sensor gap should be set. The gap should however be set to prevent the face of the sensor ever touching the pole wheel. A sensor should be mounted with the middle of the face side over the middle of the pole wheel. Dependent upon the wheel width, a certain degree of axial movement is permissible. However, the middle of the sensor must be at minimum in a distance of 3 mm from the edge of the pole wheel under all operating conditions. A solid and vibration free mounting of the sensor is important. Eventual sensor vibration relative to the pole wheel can induce additional output pulses. The sensors are insensitive to oil, grease etc. and can be installed in arduous conditions. Within the air gap specified the amplitude of the output signals is not influenced by the air gap. | | |
| Maintenance | Product cannot be repaired. | | |
| Transport | Product must be handled with care to prevent damage of the front face. | | |
| Storage | Product must be stored in dry conditions. The storage temperature corresponds to the operation temperature. | | |
| Disposal | Product must be disposed of properly, it must not be disposed as domestic waste. | | |

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