

OPERATING INSTRUCTIONS

Dual Channel Hall Effect Speed Sensor DSY 1225.02 PHW



Product ID							
	Type #	Product #	Drawing #				
	DSY 1225 02 PHW	3747-05520	114 351 Rev 06				
	2011220.021111	0112 00020					
General							
Function	The DSY 1225.02 PHW	speed sensors are suit	table, in conjunction with a pole				
	wheel, for generating square wave signals proportional to rotary speeds. They						
	have a static behaviour,	have a static behaviour, i.e. the pulse generation is guaranteed down to a speed					
	corresponding to a frequency of 0 Hz. The monitoring elements consist of						
magnetically biased hall effect semiconductors. The internal two o							
Technical data	structure requires that the sensor must be oriented according to the dra						
Technical data							
Supply voltage	8 V to 32 V, protected against reverse polarity and transient overvoltage						
Current consumption	Max. 20 mA (without loa	d)					
Signal output	 2 phase shifted squar 	e wave signals, minim	um edge shift with a customer				
	wheel: minimal 20° be	etween output 1 (S1) a	nd output 2 (S2); consult JAQUE I				
	for other pole wheels		00.4				
• Open collector outputs with $10K\Omega$ pull-up, Imax = -20mA							
	The outputs are short circuit proof and protected against reverse polarity.						
Frequency range	U HZ 15 KHZ		000.0				
	According to 89/336/EW	G, EN 50081-2, EN 50	U82-2:				
• Electrostatic discharge into housing, cable shield and wires: up to							
	according to IEC 61000-4-2, severity level 2						
	1 MHz to 1000 MHz a	ecording to IEC 61000	-4-3 severity level 3				
	 Electrical fast transients/bursts, coupled to sensor cable with a capacitive 						
	coupling clamp: up to +4 kV peak according to IEC 61000-4-4 severity level 4						
Housing	Stainless steel 1,4305, fr	ont side sealed herme	tically and resistant against				
3	splashing water, oil, con	ducting carbon- or ferro	ous dust and salt mist. Electronic				
	components potted in ch	emical and age proof s	synthetic resin.				
	Dimensions according to	drawing.					
Cable	FEP sheathing, 0.6mm ²	(AWG 20), outer-Ø 5.7	mm, bending radius min. 55 mm,				
	strand shielded screen (metal net), white						
	Operating temperature: -	90°C to +150°C					
Convolute	PFA						
Connector	FCI JBXSE2G04FCSDS						
Requirements for pole wheel	I oothed wheel of a mag	hetically permeable ma	aterial (e.g. Steel 1.0036)				
	oplimar performance wit	11					
	• Involute gear \sim Tooth width > 10 mm						
	 Four matrix 10 mm Side effect < 0.2 mm 						
	• Side onset < 0.2 mm						
	Sensor is optimized to operate with an customer gear						
Air gap between sensor and	Air gap between pole wh	eel (customer dear) ar	nd sensor housing				
pole wheel	0.1 0.8 mm						
Insulation	Housing and electronics	galvanically separated	(500 V/50 Hz/ 1 min)				
Protection class	IP68 (head) and IP67 (ca	able inlet)					
Vibration immunity	20 g in the range of 5 750 Hz						
Shock immunity	100 g for 11 ms, half sine	e wave					
Temperature	Operating temperature of entire sensor: -40° +125°C						

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Further Information				
Safety	All mechanical installations must be carried out by an expert. General safety requirements have to be met.			
Connection	The sensors must be connected according to sensor drawing. Sensor wires are susceptible to radiated noise. Therefore, the following points have to be considered when connecting a sensor: The sensor wires must be laid as far as possible from large electrical machines. They must not run parallel in the vicinity of power cables. The maximum permissible cable length is dependent upon the sensor voltage, the cable routing, along with cable capacitance and inductance. However, it is advantageous to keep the distance between sensor and instrument as short as possible. The sensor cable may be lengthened via a terminal box located in an 1020 connected in an 1020.			
Installation	The sensor has to be aligned to the pole wheel according to the sensor drawing. Deviations in positioning may affect the performance and decrease the noise immunity of the sensor. During installation, the smallest possible pole wheel to sensor gap should be set. The gap should however be set to prevent the face of the sensor ever touching the pole wheel. A sensor should be mounted with the middle of the face side over the middle of the pole wheel. Dependent upon the wheel width, a certain degree of axial movement is permissible. However, the middle of the sensor must be at minimum in a distance of 3 mm from the edge of the pole wheel under all operating conditions. A solid and vibration free mounting of the sensor is important. Eventual sensor vibration relative to the pole wheel can induce additional output pulses. The sensors are insensitive to oil, grease etc. and can be installed in arduous conditions. Within the air gap specified the amplitude of the output signals is not influenced by the air gap.			
Maintenance	Product cannot be repaired.			
Transport	Product must be handled with care to prevent damage of the front face.			
Storage	Product must be stored in dry conditions. The storage temperature corresponds to the operation temperature.			
Disposal	Product must be disposed of properly, it must not be disposed as domestic waste.			

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